Variational Inference for Discriminative Learning with Generative Modeling of Feature Incompletion

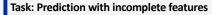
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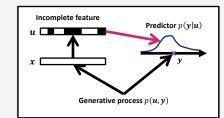
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Message

Problem of **discriminative learning** with **generative modeling** is solved with black-box variational inference (BBVI).

Summary





Example: Survival analysis

- *x* = patient's health state
- *u* = partially-missing electronic health records
- y = days to onset

Existing approaches

- Generative approach: Learn the generative process directly.
- <u>Discriminative approach</u>: Learn the predictor directly.
- <u>Hybrid approach</u>: Learn the predictor w/ generative modeling.

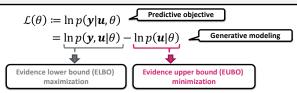
Approach		Objective	Missing-value model	Applicable models
Generative		Generative	Yes	Any generative models
Discriminati	/e	Predictive	No	Any discriminative models
Hybrid		Predictive	Yes	Predictively-trainable generative models

Problem & our solution

- <u>Problem</u>: Poor applicability of hybrid approach, i.e., absence of modelindependent algorithm.
- Our solution: Extension of black-box variational inference (BBVI).
- <u>Result</u>: Applicable to neural-network-based models (e.g., VAE).



Background: Objective function of hybrid approach



Challenge: Existing EUBOs are either biased or unstable[†]

	Unbiased	Stable
χ -bound [Dieng+ 2017]	No	Yes
Reversed KL bound [Ji & Shen 2019]	No	Yes
Tangent χ -bound [Kuleshov & Ermon 2017]	Yes	No

†: Unstable \Leftrightarrow unbounded gradient of variational lower bound:

$$VLB(\theta,\zeta) = ELBO(\theta,\zeta_1) - \left\{ f(\boldsymbol{u};\zeta_2) + \frac{1}{2} \boldsymbol{w}^2(\theta,\zeta) + C \right\}$$

where
$$\boldsymbol{w}(\theta,\zeta) \coloneqq \frac{p(\boldsymbol{u},\boldsymbol{z}|\theta)}{\exp f(\boldsymbol{u};\zeta_2) q(\boldsymbol{z}|\boldsymbol{u},\zeta_3)}$$

Proposed stabilization technique

1. Partially transform the parameter (
$$\theta$$
 and ζ_2):

$$p(\boldsymbol{u}, \boldsymbol{z}|\boldsymbol{\theta}) \mapsto p(\boldsymbol{u}, \boldsymbol{z}|\boldsymbol{\theta}') \coloneqq \frac{G(\boldsymbol{w}(\boldsymbol{\theta}, \zeta))}{Z(\boldsymbol{\theta}, \zeta)} p(\boldsymbol{u}, \boldsymbol{z}|\boldsymbol{\theta})$$
$$f(\boldsymbol{u}; \zeta_2) \mapsto f(\boldsymbol{u}; \zeta_2') \coloneqq f(\boldsymbol{u}; \zeta_2) - \ln Z(\boldsymbol{\theta}, \zeta)$$

2. Divergent term is stabilized (if G(w) is appropriate)

$$w(\theta', (\zeta_1, \zeta'_2, \zeta_3)) = \frac{p(\boldsymbol{u}, \boldsymbol{z}|\theta')}{\exp f(\boldsymbol{u}, \zeta'_2) q(\boldsymbol{z}|\boldsymbol{u}, \zeta_3)} = w(\theta, \zeta) G(w(\theta, \zeta))$$

Theoretical justification

Put $T(\theta, \zeta) \coloneqq (\theta', (\zeta_1, \zeta'_2, \zeta_3))$. Then,

1. The gradient becomes bounded:

 $\|\nabla(VLB \circ T)(\theta, \zeta)\| \le 9K$

$$K := \|\nabla \ln p(\mathbf{y}, \mathbf{u}|\theta)\| \vee \|\nabla \ln p(\mathbf{u}|\theta)\| \vee \|\nabla f(\mathbf{u}, \zeta)\|$$
$$\vee \|\nabla \ln q(\mathbf{z}|\mathbf{u}, \zeta)\| \vee \|\nabla \ln q(\mathbf{z}'|\mathbf{y}, \mathbf{u}, \zeta)\|$$

2. "Effective" parameters are preserved and invariant:

$$\Theta_{\rm eff}(T(\Omega)) = \Theta_{\rm eff}(\Omega),$$

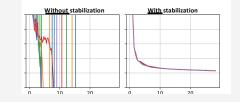
where

where

$$\Theta_{\rm eff}(\Omega) \coloneqq \{(\theta,\zeta) \in \Omega : \mathcal{L}(\theta) = \mathbb{E}_{z}[VLB(\theta,\zeta)]\}.$$

Experimental results

Comparison of stability (training objective)



Comparison of predictive performance w/ VAE

